

Agilent E8491B

Increasing Test System Throughput with IEEE 1394

Application Note



Agilent Technologies

Innovating the HP Way

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Part I: Measuring Real Test I/O Throughput

Introduction

IEEE-1394 (“FireWire”) technology is an open, scalable, flexible, plug-and-play, low-cost serial interface that is being widely adopted in digital consumer products and personal computers.

This high-speed serial bus has prompted many test departments to determine how FireWire can be used to connect instruments to computers for test control. Test environments are discovering that FireWire is ideally suited to test and measurement applications, allowing significant reductions in the cost of test.

By moving data faster with large data block transfers, test time—and consequently the cost of test—is reduced. Other cost reductions are achieved in part because serial data transfer allows the use of a simplified cable design: the IEEE-1394 high-speed serial bus uses a thin, flexible, inexpensive cable to provide a fast, easy connection between computers and external peripherals. Another cost reduction comes from simplification of the electronics: the transmitters and receivers in the standard chip set handle addressing, initialization, arbitration and protocols, keeping the cost of IEEE-1394 technology low.

The E8491B is Agilent Technologies’ implementation of FireWire technology for test and measurement applications. This IEEE-1394 PC-Link to the VXI interface ships as a C-size, 1-slot, message-based VXI module. The implementation introduces a variety of advantages as a Slot 0 control solution in the VXI market:

- It is capable of handling the Resource Manager and Slot 0 responsibilities.
- It can transfer data blocks greater than 64 kilobytes at 14 megabytes per second, five times faster than its predecessor.
- It eases configuration with the automatic recognition feature called “hot-plugging,” which allows the host system to automatically recognize an IEEE-1394-based device without powering down the PC.
- It’s scalable, supporting up to 16 mainframes using daisy chain or star configurations.
- Its data block transfer capability increases throughput performance well beyond that of GPIB at a much lower price than MXI, with results that match embedded solutions.

In terms of architecture, price, and speed, FireWire and embedded solutions are quickly becoming the dominant choices in Slot 0 control.

System Throughput Benchmarks

Getting a true objective measurement of throughput can be difficult. Published specifications that measure only part of the test throughput equation don’t tell a complete story.

In throughput testing, the speed of the interface sending a command to the target device is very often the only consideration. But by merely testing the throughput of one element of a real test, false conclusions can result: other elements of the test that are critical to throughput are often ignored, and opportunities to improve throughput are often missed.

In the real world of test and measurement, the time to send a command to a working device, take a reading, and return it for display or output is a more complete test for system throughput. So while the test of the technology with infinitely fast instruments is addressed in this document (see Appendix I and II), the real measure of I/O throughput is the system throughput benchmark. The test cases described in the following pages illustrate the throughput benchmark for actual test measurements.

Innovations to FireWire Technology

FireWire transmits “packets” of data in big blocks, much like a local area network (LAN). Because of the serial nature of data transmission, first-byte latency—or the time it takes to transfer the first byte after the command to initiate is given—is an issue relevant to throughput. Each data packet carries this overhead of latency, contributing to the total throughput elapsed time. If each packet contains one read/write instruction like the typical GPIB controller, the overhead results in slow throughput.

The unique big-block aspects of FireWire technology allow multiple transactions per packet. This reduces the impact of first-byte latency: more data can be carried by a given packet, leading to decreased packet count. Engineers developed additional, higher level protocols, and optimized bit- and byte-ordering, data transmission, and error detection and correction of the bit stream. These modifications contributed to dramatic improvements in real throughput of IEEE-1394 for test and measurement applications.

Test Cases

Agilent has benchmarked the typical classes of measurement, from sending the command to setting up the instrument, to taking the measurement itself, to the storage or display of measurements. The benchmarks use typical instruments to perform the kinds of tests commonly seen in data acquisition and functional test applications. The benchmarks involve configuring real instruments, taking a sample, and transferring the sample. The Slot 0 controllers are the E8491B FireWire Card, the E1406B GPIB Card, the NI VXI-PCI8015 MXI-2 Card, and the E6235A Embedded 200 MHz PC. A 200 MHz Kayak XU PC was the external PC. The programming language used for all the cases was C++. The operating system used by the computers was Microsoft® Windows NT®.

Small Block Measurements

The first benchmark is for a register-based data acquisition system sampling various waveforms. In this test, the test system configures an E1563A digitizer to sample waveforms in 1K, 4K, 8K, 16K, and 1M sample sizes. Then the system transfers the data.

The most interesting of these benchmarks involves smaller block transfers of 1K, as shown in Chart 1. IEEE-1394 technology is noted for its throughput on large blocks; in this benchmark, small block transfers were also very cost-effective. Actual measurements for 1K, 8K, 16K, and 1M are available on the Agilent test and measurement web site, along with a complete set of benchmark results. The site is located at www.tmo.agilent.com/tmo/techinfo/English/EFT_Benchmarks_FireWire.html.

In an application such as antenna test, where speeds faster than GPIB would improve test time, an E8491B FireWire connection provides a 4X improvement in performance. Yet, this improvement costs only 10 percent more than GPIB. Note that MXI-2 provides only a marginal improvement in throughput over the E8491B at nearly twice the price.

Also note the throughput at a sample size of 8K (Chart 2). The efficiency of the IEEE-1394 technology begins to match that of MXI-2 and embedded controllers. For a wide variety of applications, the E8491B is the most cost-effective solution, even when transferring relatively small blocks of data.

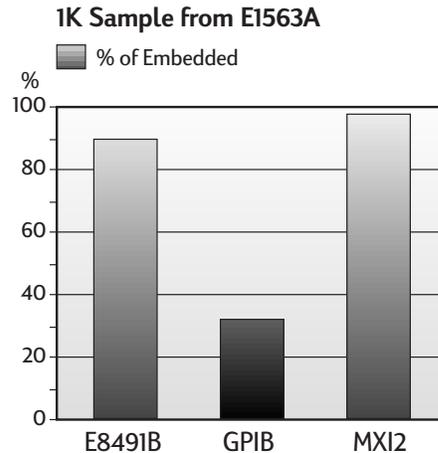


Chart 1

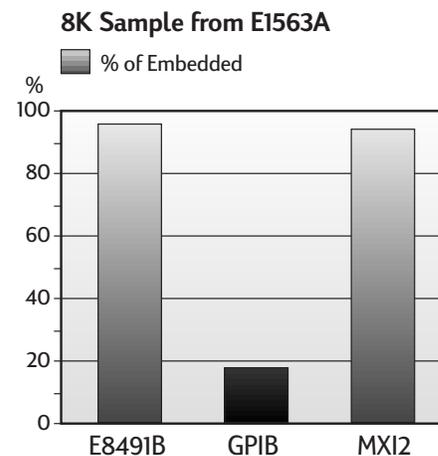


Chart 2

High Channel Count

Charts 3 and 4 show results of another solution where the IEEE-1394 technology provides increased throughput at a lower cost in a register-based data acquisition system requiring a large number of channels and continuous data acquisition. This solution uses the direct register-based protocol that communicates at a lower level than message-based devices.

In this test, a system scans with three E1413C 64-Channel Scanning A/D Converters, a configuration that provides the volume of channels required by many of today's manufacturing lines. The E1406A GPIB module does not transfer quickly enough to support multiple E1413Cs, whereas IEEE-1394, MXI-2, and embedded PC all support the configuration. These three options, while close in throughput, are widely divergent in price.

The E8491B-based solution is the value leader, providing virtually the same performance as an embedded PC at a fraction of the cost. The E8491B-based solution is actually faster than MXI-2 in this application.

Functional Test Peek & Poke

Chart 5 demonstrates the results of "peek and poke" measurement times in functional test applications. This test simulates worst-case results for the IEEE-1394 technology. In this test, an E1330B Digital I/O inputs or outputs a control signal; an E8460A Multiplexer opens one switch and closes another; an E1411B DMM changes function and range, then takes one reading. The E8491B provides the low cost solution with a 40 percent improvement over GPIB. For high speed requirements, the embedded solution provides an open architecture with a smaller footprint for manufacturing applications.

64 Readings @ 100 kHz Rate

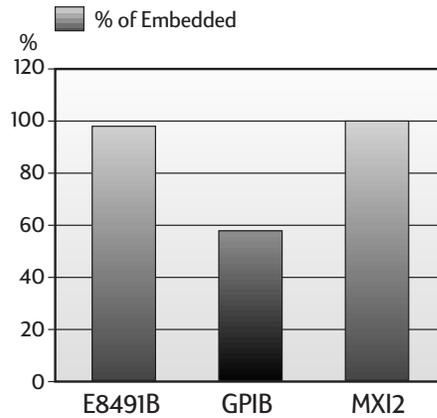


Chart 3

50K Readings @ 100 kHz Rate

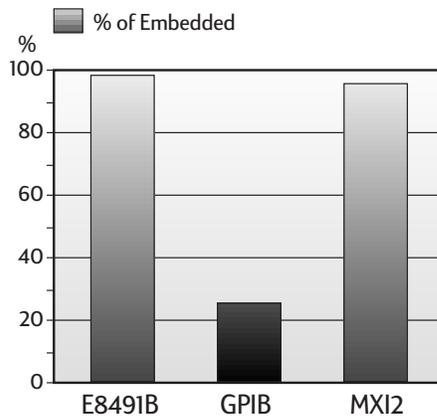


Chart 4

Register Based Electronic Functional Test

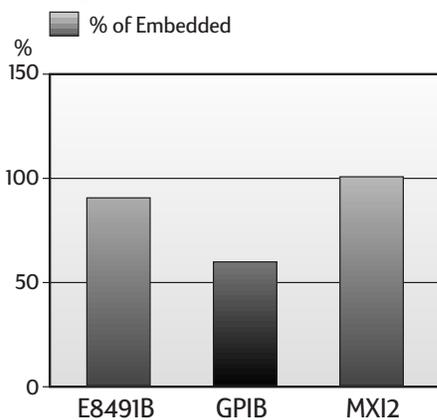


Chart 5

Functional Test Scanning

This case shows the performance of the various solutions in an application that is particularly suited for a system based on the E8491B. This system allows the E1411B DMM to configure the E8460A Multiplexer as a scanning multimeter. The volt-meter commands will automatically control the switch cards that are assigned to it. This greatly simplifies programming and accelerates instrument operation. This is particularly useful to applications where multiple units are involved, such as cable and battery test.

Since Agilent-generated drivers produce fewer packets, the cumulative time to process packets is reduced, as is the cumulative first-byte latency of a test. Data transfers also take advantage of the large-block transfer capability of IEEE-1394 technology, so the E8491B interface shows numbers that are very competitive with other alternatives in this test class.

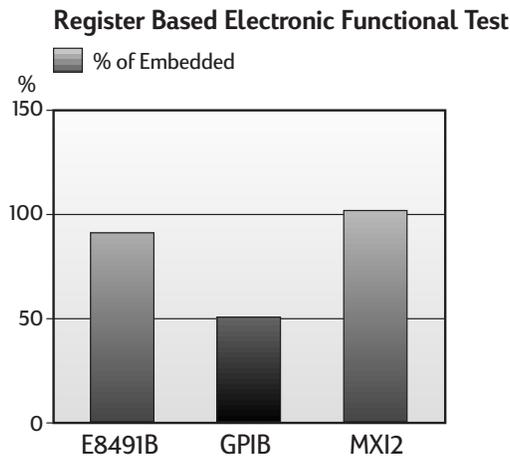


Chart 6

Summary

IEEE-1394 technology presents an opportunity for a significant breakthrough in test throughput. Agilent Technologies brings that opportunity to market with the E8491B FireWire Slot 0 controller, which simplifies configuration and reduces the cost of test.

The methods for benchmarking the E8491B provide a true, objective view of the real-world throughput of an actual test system. The test systems used for benchmarking represent a cross-section of application architectures common to today's manufacturing test environments.

The results:

- While the IEEE-1394 technology posted predictable competitive throughput numbers for large-block applications, the E8491B implementation also proved cost effective in small-block applications.
- For tests involving setup and return of small data packets only, the interface is largely irrelevant to throughput, but note that the IEEE-1394 FireWire technology exceeds GPIB in throughput at about the same price.
- For tests involving a mixture of large and small packets, IEEE-1394 FireWire is the value leader in low cost solutions, far exceeding GPIB in performance. At the direct connection to the backplane, the embedded solution provides open, integrated architecture and a smaller footprint.

The new E8491B PC-Link-to-VXI data block transfer capability increases throughput performance well beyond that of GPIB at a price that is far more attractive than MXI-2. In terms of architecture, price and speed, FireWire and embedded solutions are quickly becoming the dominant choices in Slot 0 control.

Part II: Understanding VXI Slot 0 I/O Benchmarking

Benchmark

Agilent Technologies' benchmark numbers indicate that the E8491B with FireWire technology has the potential to be the dominant solution in Slot 0 control. This section discusses the elements of the benchmark test and proves the veracity of the results achieved by Agilent.

Fundamentals

The benchmark measures the time it takes to send a command across the interface and backplane to an instrument, and receive the data back. Three steps are involved: configure, sample or scan, and data transfer.

- The configure period measures the time required to initiate a command and send it to an instrument.
- The sample or scan period measures the total time required for the instrument to match the command configuration and act on the command it received. Note that this time is instrument-dependent, and is independent of the interface being used.
- The transfer period measures the time when the instrument is reporting on the data it collected from the device under test (DUT).

Configure

The characteristics of the configure period are determined by the communication method of the instrument, either word serial protocol, random reads/writes, or block transfer.

- **VXI Word Serial Protocol**
Message-based devices communicate with each other using a standardized procedure known as "word serial protocol." This asynchronous protocol defines the handshake necessary to move commands and data between devices. It provides a reliable, standardized way to communicate with devices, but at the cost of lower throughput. This is because transferring each byte of a command string requires a minimum of three 16-bit data accesses. Also, most message-based device command strings are based on long human-readable ASCII commands such as IEEE-488.2 or SCPI commands. So for a communication cycle of a small data packet, the interface throughput is not significant to the throughput of a VXI word serial operation.

- **Random Reads/Writes**

VXI also provides another, faster type of instrument: register-based devices. Register-based devices communicate at a lower, more basic level than message-based devices, so they can attain greater transfer speeds than message-based instruments. Registers are high-speed memory locations that interface directly to an instrument's on-board control logic with reads and writes using binary information. Each read or write can directly affect the programming state of the device, with no interpretation required. A read/write operation sends simple one-, two- or four-byte data across the VXI bus to non-sequential registers in VXI shared memory or an instrument register set.

- **Block Transfers**

The best example of this is an instrument with a FIFO buffer for data storage. The instrument converts a measurement to its binary equivalent and stores the values to its FIFO. The VXI controller moves this block of data from the FIFO to its local memory. This operation is called the block data transfer.

There is the overhead of setting up each transfer. For that reason the size of the block is critical to the performance enhancement that IEEE-1394 controllers can provide. The use of shared memory and FIFO buffers enable the large-packet size that makes the system faster and reduces the cost of test. The bigger the block due to a large amount of data or a complicated setup command, the smaller percentage the overhead contributes to overall throughput.

Sample or Scan

During this period the instrument matches the configuration it received and takes action. This period is instrument-dependent and is independent of the interface being used. The width (one, two, or four bytes) of the sample or scan, and their location in the program, vary among instruments and can affect throughput.

Transfer

At this stage, the system has executed the command and is ready to transfer the data. The transfer period is the time it takes to move the data from the device to storage, or to another location for display. Once the instrument is ready to transmit the packet, throughput depends on the performance of the interface.

With the three areas of focus established, the next consideration is the test. A true “apples to apples” comparison is usually achieved by standardizing the devices and simplifying the test. There is no danger in standardizing the devices, but simplifying the test can lead to false conclusions. To reduce that risk, the Agilent benchmark tests not only the throughput of the communication protocols, but also the system throughput.

System Throughput

System performance depends on the components that make up the system. Each component contributes the time of its operation to the total time of a cycle. Drivers that take advantage of the inherent characteristics of IEEE-1394 technology can package data to greatly improve performance. Once the driver is optimized for throughput, opportunities that arise on the backplane stretch the technology for performance enhancements. Together, these multiple enhancements, with their different contributions, can more efficiently fill the data bus. This makes for higher overall system throughput, so a system throughput benchmark is a more complete measure of performance.

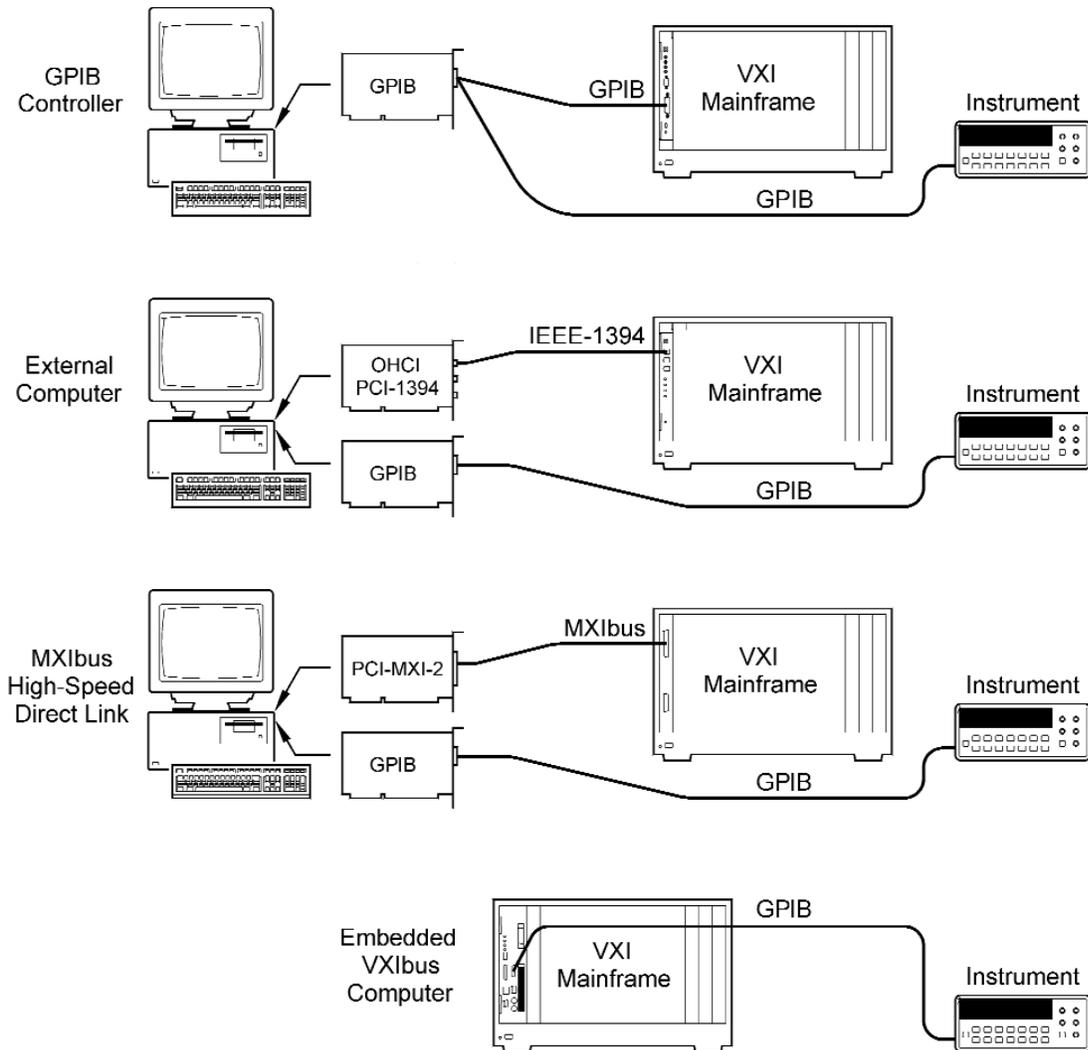


Figure 1. Controller Configurations

Controller Configurations

Four basic interface methods (Figure 1) span the range of configurations for connecting to VXI. The traditional method is the GPIB connection between the computer and the VXI Slot 0 card. A card in the controller connects to the GPIB Slot 0 card by a GPIB cable. The IEEE-1394 card fits in Slot 0 of the VXI mainframe with a PCI card in the computer connected by the IEEE-1394 cable. The MXI method connects the controller to the VXI bus through a multi-wire cable much like GPIB. The most direct connection is the embedded controller that fits in Slot 0 of the VXI mainframe and connects directly to the VXIbus.

GPIB

This method of connection uses the same application software and drivers used to program instruments in the rack-and-stack environment. Using GPIB, the computer transmits through the GPIB Interface card across a heavy GPIB cable to a command module in Slot 0 of the VXI mainframe. This VXI module translates data to and from the VXI word serial protocol. Figure 2 illustrates the method. The computer transmits a string to a VXI instrument. The command module determines the device address and sends the string to the appropriate instrument using word serial protocol.

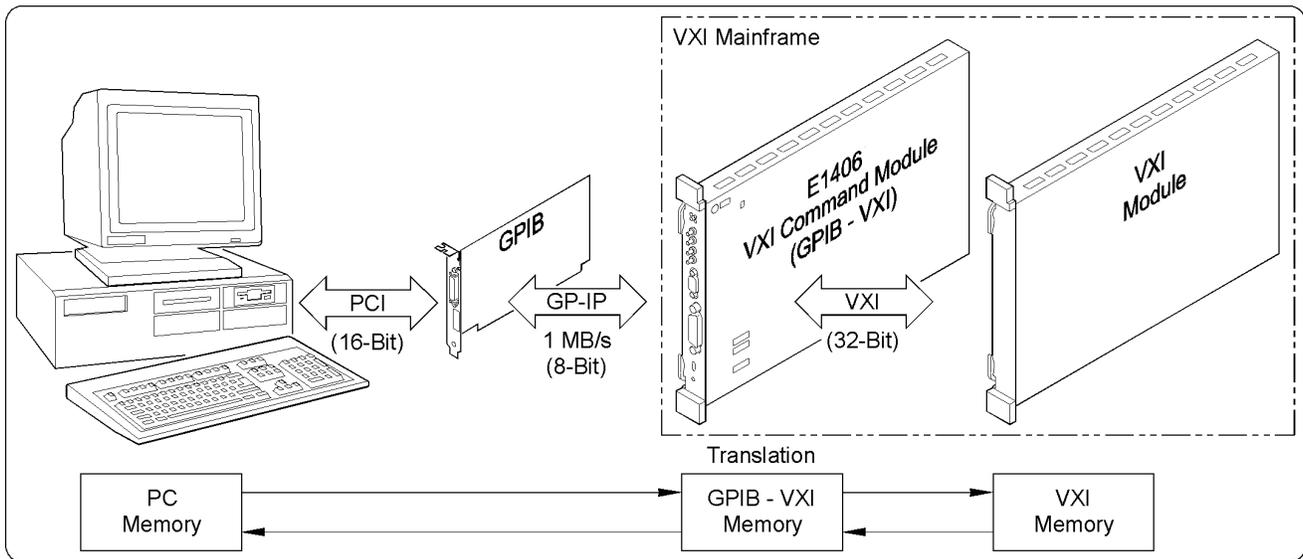


Figure 2. GPIB-VXI Architecture

In message-based instruments, the command module only needs to translate the GPIB protocol to word serial protocol. For register-based devices, the command module must interpret the string and convert it into register reads/writes that are appropriate for the device.

This additional transaction for register-based instruments makes GPIB a much slower controller method than the others. VXI systems using GPIB will never reach the maximum throughput because of the translations and interpretation of the relatively slow command module.

FireWire

The Agilent E8491B controller configuration consists of a VXI Slot 0 controller, a thin, flexible serial cable, and an expansion board that plugs into the PCI expansion slot of a computer. Figure 3 illustrates the communication method. Note that the remote computer transmits a string to a VXI instrument. Data is serialized at the PCI expansion card and IEEE-1394 data packets are created. Packets travel across the cable and are made into parallel data in the E8491B interface. The E8491B converts the packet data to either word serial protocol or random reads/writes, determines the device address, and sends the string down the backplane to the appropriate instrument.

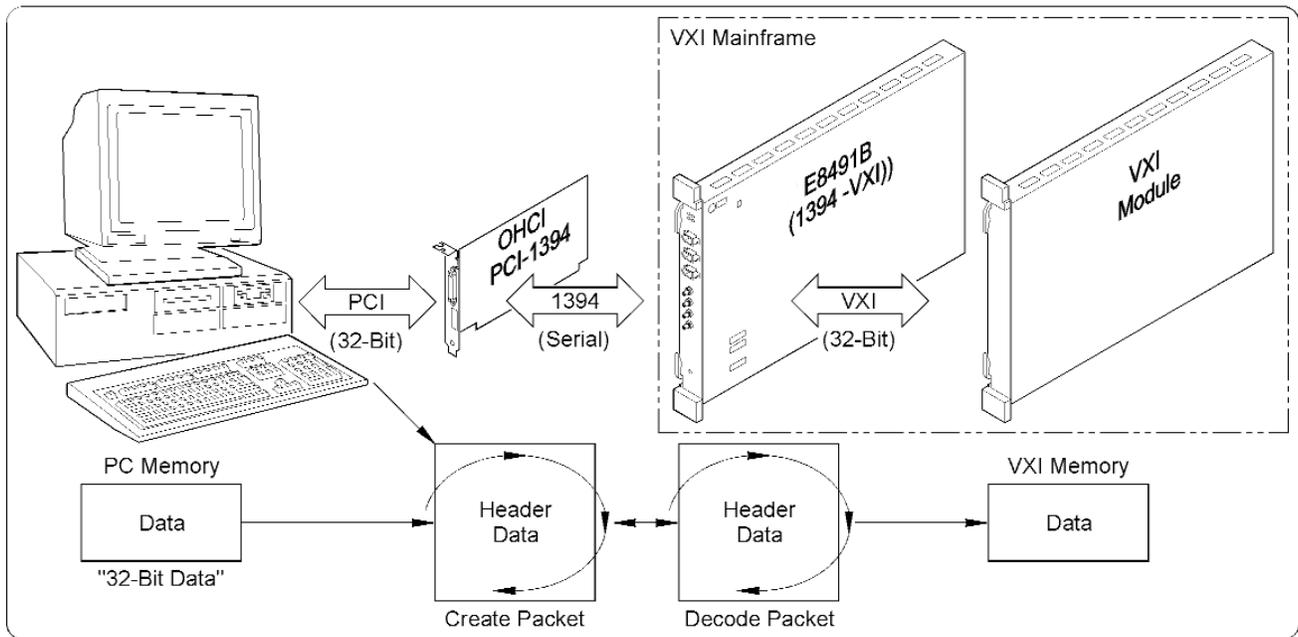


Figure 3. IEEE-1394 Architecture

Because of the nature of the serial bus, the IEEE-1394 protocol must turn data into packets, arbitrate for the bus, and gain VXI memory access. This creates the first-byte latency for the IEEE-1394 protocol. To minimize the impact of first-byte latency, the E8491B solution optimizes the PCI card, includes drivers to pass a macro of commands rather than individual commands, and turns interrupts off.

MXI interface performance is highly dependent on the expansion bus and microprocessor in the computer. The PCI bus provides 32-bit bi-directional transfers with throughput that is well in excess of the ISA bus 16-bit transfer. The faster the microprocessor, the faster the overhead associated with random reads and writes, and the faster word serial transfers are processed.

MXI

The MXI system is illustrated in Figure 4. It connects the controller bus to the VXI bus in much the same way as the previous methods. An on-board card in the computer connects through a large cable to the special MXI Slot 0 card. Data moves in parallel transfers between the buses by directly converting the data cycles in hardware. No time is spent creating packets or command strings.

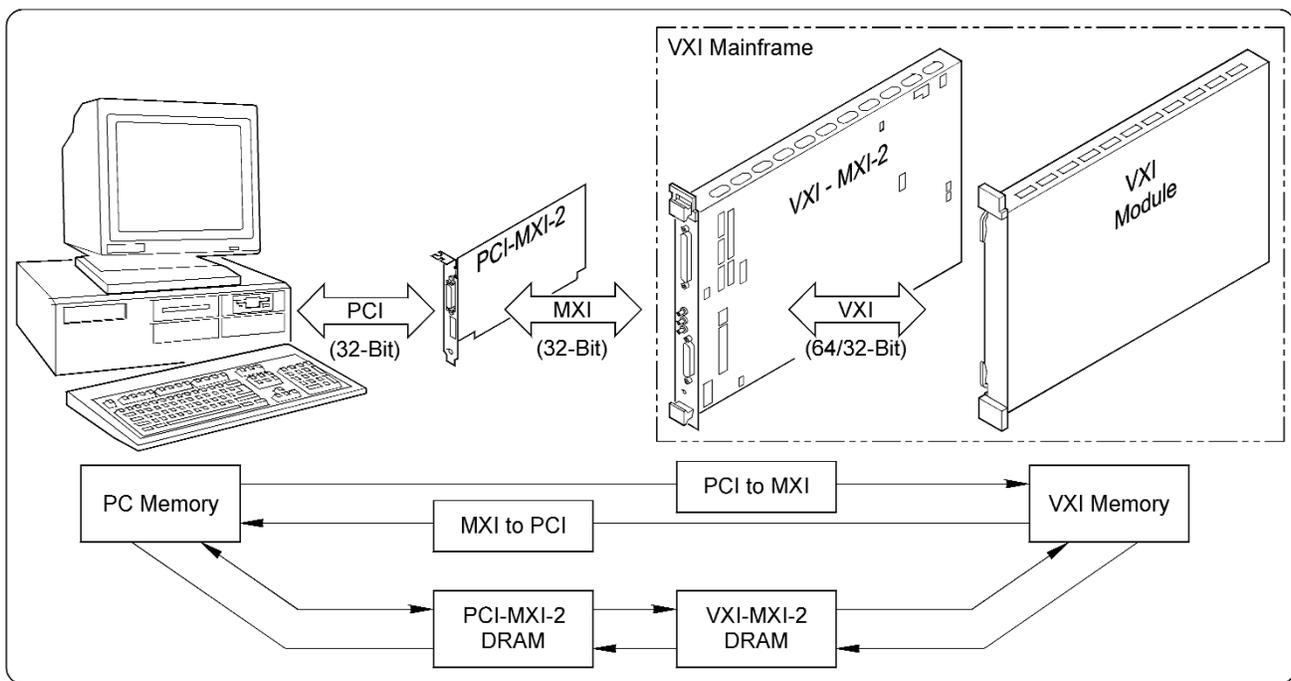


Figure 4. MXI-2 Architecture

Embedded VXI Controller

In the embedded VXI controller configuration shown in Figure 5, the controller is physically located in Slot 0 of the VXI chassis. This configuration connects the controller directly to the VXI bus, allowing the controller to access all signals on the backplane. There is lower overhead for transactions since software translations are eliminated due to the direct read/write of the registers for both message- and register-based instruments. Binary data is transferred in parallel to and from the instrument at high speed.

The embedded VXI controller is built on a VXI card format. It is a specialized type of controller based on the PC specifications. It is the smallest connection, giving it a footprint advantage over other methods. Direct connection to VXIbus also provides a throughput advantage.

Conclusion

For most manufacturers, there is a dire need to test faster and reduce the cost of test. FireWire technology offers an opportunity to do just that. The E8491B uses the inherent characteristics of IEEE-1394 technology to improve throughput between instrument and controller for test and measurement applications. With the best price/performance ratio of any VXI-based instrument control solution, the E8491B has the potential to become the dominant Slot 0 solution on the market. It is part of Agilent Technologies' ongoing strategy to bring new innovations to market that advance the state-of-the-art in open systems architectures and VXI technologies, with complete solutions that are easy to use, easy to buy, and easy to afford.

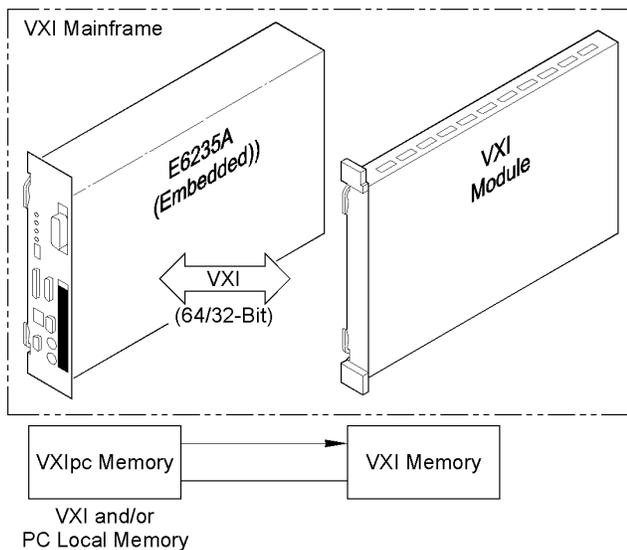


Figure 5. Embedded Controller Architecture

Appendix I

Theoretical Performance

It is useful to look at theoretical and infinitely fast instruments to see why system throughput is the practical way to evaluate performance. Theoretical maximum transfer rate shown in Table 1 describes the data rate to and from an infinitely fast instrument. The first-byte latency is the elapsed time from the beginning of the instruction to transfer the first byte to the actual transfer across the link.

Measuring maximum transfer rate and first-byte latency alone do not provide a representative overall transfer rate for a system because they only measure the time to the start of an instruction. This leaves out, among other things, the time to transfer the sample.

In the 8K waveform shown in Table 2 scanning benchmark, the transfer of the sample takes more time than the configure step. As noted, the sample rate is instrument-dependent, but the transfer rate is certainly dependent on the interface. Any useful benchmark must include the time of the transfer of a reading.

Performance Factors

Theoretical maximum throughput and first-byte latency do not take into consideration other factors that impact the performance of the system. One of those factors is context switching. The context-switching period is the time a multitasking operating system uses to stop running one process and start running another. This period must be added to the total throughput. Related activities such as interrupts and I/O drivers also make a contribution to the throughput totals. Architecture of the operating system dictates the duration of many of these activities, but variations between operating systems are very small.

The environment itself will make a contribution. Applications developed in a compiled environment make less of an impact on transfer speeds than those developed in an interpreted environment. Interpreted environments must analyze each statement in the program each time it is executed. In compiled environments, analysis is done at the conversion of a program to machine code. Doing the analysis at the time of compiling in conjunction with faster-executing machine code allow programs from compiled environments to execute faster than programs from interpreted environments.

The final factor affecting system performance is the speed of the target device. The speed of the measurement, the width of the reading in bytes, and the location of the measurement in the test programs combine to affect the overall throughput.

Table 1. Theoretical Performance

	Embedded	GPIB	MXI-2	IEEE-1394
Max Transfer Rate	80 Mbytes/s (VME64)	1 Mbytes/s	33 Mbytes/s	43 Mbytes/s
First-Byte Latency	80 ns	120 μ s	1 μ s	150 μ s

Table 2. Actual System Performance

Time In MS	Embedded	GPIB	MXI-2	IEEE-1394
Configure	0.21	29.17	0.18	3.55
Sample	117.78	119.57	117.35	117.59
Transfer	4.11	490.27	12.65	5.76
Total	122.10	639.01	130.18	126.90

VXI Contribution

The VXIbus backplane has a theoretical data transfer limit of 40 Mbytes per second. Normally, the backplane will not be a bottleneck for a data transfer. The not-so-obvious advantage of the VXIbus is its potential for distributed intelligence, which leads to increased system throughput. Because of its VMEbus background, VXIbus can deal with multiple microprocessors on the backplane existing within a shared memory architecture. Multiple levels of priority allow critical processes to interrupt and use resources only when they are required. This capability, when combined with creative use of drivers, created the opportunity to dramatically improve throughput and the price/performance impact of the Agilent E8491B.

Appendix II

E8491B Details

The interface improves data transfer throughput where data can be sent in large blocks. This is particularly convenient for data acquisition instruments. These instruments can take advantage of the E8491B's tremendous throughput to transfer information from the instrument to computer without saturating the bus.

For purposes of comparison, Table 1 shows the performance of the E8491B with an infinitely fast instrument. This benchmark shows the time in microseconds (μs) it takes for the computer to prepare and send a command over the backplane. This time is then computed into a rate expressed in kilobytes per second.

Table 1 shows that moving blocks of data with the E8491B is a more efficient way to transfer data than using single read/writes. When an application requires that several bytes of data be sent to separate locations, standard VISA I/O libraries do not provide a mechanism for combining these operations into a single block operation. Macro technology created by our R&D Engineers provides this mechanism.

By packing several write commands into a macro rather than sending individual writes, considerable improvement in throughput is achieved. Table 2 shows the advantages of this alternative by showing macro speeds compared to individual read/writes. The times indicate that the macros are a higher performance alternative to individual read/writes.

Table 1. Shorted Benchmarks

Commands	Transfer Type	Transfer Size (Bytes)	Time (μs)	Rate (kBytes/s)
ViPeek16	16 bit read	2	130	15
ViMoveIn16	16 bit read	16	170	94
	16 bit read	4096	1110	3690
	16 bit read	122880	12300	9760
viMoveIn32	32 bit read	122880	8390	14300
iblockmovex64 read	64 bit read	122880	8330	14400
ViSend	Word Serial Message	128	1600	20

Table 2. Comparison of individual vs. macro read/write performance

# Writes	ViPoke16 (μs) (Individual Write)	Macro (μs) (Combined Writes)	Macro Advantage
1	200	240	-40
2	400	250	150
3	600	250	350
4	790	260	530
5	990	270	720
6	1200	280	920
16	3200	390	2810

Features of the IEEE-1394 Bus

The following features of the IEEE-1394 bus apply to all bus applications including VXI systems.

- Daisy chain or branching configurations are allowed. There can be no closed loops (i.e. more than one connection between any two devices).
- Up to 63 devices (including 16 E8491Bs) are allowed per bus segment. One host adapter represents one bus segment.
- There is a maximum of 16 hops* between any two devices. The bus cable length cannot exceed 72 meters between any two devices.
- Live/hot connections. A VXI mainframe anywhere in the configuration can be turned on/off at any time without affecting the other mainframes. The IEEE-1394 bus automatically reconfigures itself any time a VXI mainframe (or other device) is added or removed.

*A hop is an IEEE-1394 cable link between nodes.

Other Advantages

Other advantages of an IEEE-1394 VXI Slot 0 module are built-in support and more flexible cabling.

Both Intel and Microsoft have endorsed IEEE-1394 and use it as one of two serial buses as part of the sealed PC concept. Microsoft has built-in support for IEEE-1394 in Windows 98® and the upcoming Windows 2000®.

Cabling is another benefit for instrumentation: flexible cable and bridging structure with IEEE-1394 allows instruments and controllers to be placed in desired locations instead of being limited by cable length and flexibility.

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